

CS 430/536
Computer Graphics I

Line Drawing

Week 1, Lecture 2

David Breen, William Regli and Maxim Peysakhov
Geometric and Intelligent Computing Laboratory
Department of Computer Science
Drexel University
<http://gicl.cs.drexel.edu>



Outline

- Math refresher
- Line drawing
- Digital differential analyzer
- Bresenham's algorithm
- XPM file format

2

Geometric Preliminaries

- **Affine Geometry**
 - Scalars + Points + Vectors and their ops
- **Euclidian Geometry**
 - Affine Geometry lacks angles, distance
 - New op: Inner/Dot product, which gives
 - Length, distance, normalization
 - Angle, Orthogonality, Orthogonal projection
- **Projective Geometry**

3

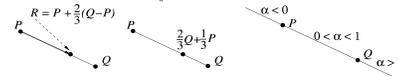
Affine Geometry

- **Affine Operations:**



vector ← scalar · vector, vector ← vector / scalar
vector ← vector + vector, vector ← vector - vector
vector ← point - point, point ← point - vector
point ← point + vector, point ← point - vector

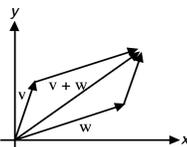
- **Affine Combinations:** $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n$
where v_1, v_2, \dots, v_n are vectors and $\sum_i \alpha_i = 1$
Example: $R = (1 - \alpha)P + \alpha Q$



4

Mathematical Preliminaries

- Vector: an n -tuple of real numbers
- Vector Operations
 - Vector addition: $u + v = w$
 - Commutative, associative, identity element (0)
 - Scalar multiplication: cv



- **Note: Vectors and Points are different**
 - Can not add points
 - Can find the vector between two points

5

Linear Combinations & Dot Products

- A **linear combination** of the vectors v_1, v_2, \dots, v_n is any vector of the form $\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n$ where α_i is a real number (i.e. a scalar)

- **Dot Product:**

$$u \cdot v = \sum_{k=1}^n u_k v_k$$

a real value $u_1 v_1 + u_2 v_2 + \dots + u_n v_n$ written as $u \cdot v$

6

Fun with Dot Products

- **Euclidian Distance** from (x,y) to $(0,0)$
 $\sqrt{x^2 + y^2}$ in general: $\sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$
 which is just: $\sqrt{\vec{x} \cdot \vec{x}}$
- This is also the length of vector \underline{v} :
 $||\underline{v}||$ or $|\underline{v}|$
- **Normalization** of a vector: $\hat{v} = \frac{\vec{v}}{|\vec{v}|}$.
- **Orthogonal** vectors: $\vec{u} \cdot \vec{v} = 0$

7

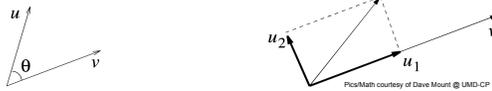
Projections & Angles

- **Angle between vectors, θ** $\vec{u} \cdot \vec{v} = |\vec{u}||\vec{v}|\cos(\theta)$

$$\theta = \text{ang}(\vec{u}, \vec{v}) = \cos^{-1} \left(\frac{\vec{u} \cdot \vec{v}}{|\vec{u}||\vec{v}|} \right) = \cos^{-1}(\hat{u} \cdot \hat{v}).$$

- **Projection of vectors**

$$\vec{u}_1 = \frac{(\vec{u} \cdot \vec{v})}{(\vec{v} \cdot \vec{v})} \vec{v} \quad \vec{u}_2 = \vec{u} - \vec{u}_1.$$



PicaMath courtesy of Dave Mount @ UMD-CP

Matrices and Matrix Operators

- A n -dimensional vector:

$$\begin{bmatrix} x_1 \\ \cdot \\ \cdot \\ \cdot \\ x_n \end{bmatrix}$$

- **Matrix Operations:**
 - Addition/Subtraction
 - Identity
 - Multiplication
 - Scalar
 - Matrix Multiplication

- **Implementation issue:**
 Where does the index start?
 (0 or 1, it's up to you...)

$$\begin{aligned} A + B &= B + A \\ A + (B + C) &= (A + B) + C \\ (cd)A &= c(dA) \\ 1A &= A \\ c(A + B) &= cA + cB \\ (c + d)A &= cA + dA \end{aligned}$$

9

Matrix Multiplication

- $[C] = [A][B]$
- Sum over rows & columns
- Recall: matrix multiplication is *not* commutative
- **Identity Matrix:**
 1s on diagonal $c_{ij} = \sum_{s=1}^m a_{is}b_{sj}$
 0s everywhere else

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ a_{21} & a_{22} & a_{23} & a_{24} \\ a_{31} & a_{32} & a_{33} & a_{34} \\ a_{41} & a_{42} & a_{43} & a_{44} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & b_{13} & b_{14} \\ b_{21} & b_{22} & b_{23} & b_{24} \\ b_{31} & b_{32} & b_{33} & b_{34} \\ b_{41} & b_{42} & b_{43} & b_{44} \end{bmatrix} \begin{bmatrix} c_{11} & c_{12} & c_{13} & c_{14} \\ c_{21} & c_{22} & c_{23} & c_{24} \\ c_{31} & c_{32} & c_{33} & c_{34} \\ c_{41} & c_{42} & c_{43} & c_{44} \end{bmatrix}$$

10

Matrix Determinants

- A single real number
- Computed recursively $\det(A) = \sum_{j=1}^n A_{i,j}(-1)^{i+j} M_{i,j}$
- Example: $\det \begin{bmatrix} a & c \\ b & d \end{bmatrix} = ad - bc$
- **Uses:**
 - Find vector ortho to two other vectors
 - Determine the plane of a polygon



11

Cross Product

- Given two non-parallel vectors, A and B
- $A \times B$ calculates third vector C that is orthogonal to A and B
- $A \times B = (a_y b_z - a_z b_y, a_z b_x - a_x b_z, a_x b_y - a_y b_x)$

$$A \times B = \begin{vmatrix} \vec{x} & \vec{y} & \vec{z} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

12

Matrix Transpose & Inverse

- **Matrix Transpose:** Swap rows and cols: $A = \begin{bmatrix} 2 \\ 8 \end{bmatrix}$ $A^T = \begin{bmatrix} 2 & 8 \end{bmatrix}$
- Facts about the transpose: $(A^T)^T = A$
 $(A + B)^T = A^T + B^T$
 $(cA)^T = c(A^T)$
 $(AB)^T = B^T A^T$
- **Matrix Inverse:** Given A , find B such that
 $AB = BA = I$ $B \rightarrow A^{-1}$
 (only defined for square matrices)

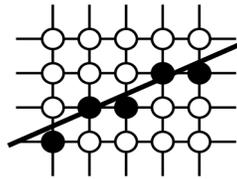
13

Line Drawing

14

Scan-Conversion Algorithms

- Scan-Conversion: Computing pixel coordinates for *ideal* line on 2D raster grid
- Pixels best visualized as circles/dots
 - Why? Monitor hardware



15

1994 Foley/VanDam/Fort/Huber/Phillips ICG

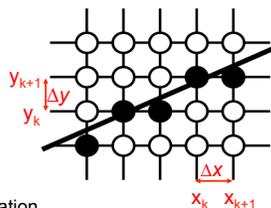
Drawing a Line

- $y = mx + B$
- $m = \Delta y / \Delta x$
- Start at leftmost x and increment by 1
 $\rightarrow \Delta x = 1$
- $y_i = \text{Round}(mx_i + B)$
- This is expensive and inefficient
- Since $\Delta x = 1$, $y_{i+1} = y_i + \Delta y = y_i + m$
 – No more multiplication!
- This leads to an incremental algorithm

16

Digital Differential Analyzer (DDA)

- If $|\text{slope}|$ is less than 1
 - $\Delta x = 1$
 - else $\Delta y = 1$
- Check for vertical line
 - $m = \infty$
- Compute corresponding Δy ($\Delta x = m$ ($1/m$))
- $x_{k+1} = x_k + \Delta x$
- $y_{k+1} = y_k + \Delta y$
- Round (x, y) for pixel location
- Issue: Would like to avoid floating point operations



17

1994 Foley/VanDam/Fort/Huber/Phillips ICG

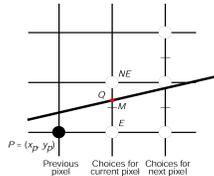
Generalizing DDA

- If $|\text{slope}|$ is less than or equal to 1
 – Ending point should be right of starting point
- If $|\text{slope}|$ is greater than 1
 – Ending point should be above starting point
- Vertical line is a special case
 $\Delta x = 0$

18

Bresenham's Algorithm

- 1965 @ IBM
- Basic Idea:
 - Only integer arithmetic
 - Incremental



- Consider the *implicit* equation for a line:

$$f(x, y) = ax + by + c = 0$$

19

1994 Foley/VanDam/Finer/Hugues/Phillips ICG

The Algorithm

```
void bresenham(IntPoint q, IntPoint r) {
    int dx, dy, D, x, y;
    dx = r.x - q.x; // line width and height
    dy = r.y - q.y;
    D = 2*dy - dx; // initial decision value
    y = q.y; // start at (q.x, q.y)
    for (x = q.x; x <= r.x; x++) {
        writePixel(x, y);
        if (D <= 0) D += 2*dy; // below midpoint - go to E
        else { D += 2*(dy - dx); y++; // above midpoint - go to NE
        }
    }
}
```

Assumptions: $q_x < r_x$
 $0 \leq \text{slope} \leq 1$

Pre-computed: $2d_y$ $2(d_y - d_x)$

20

PicaMath courtesy of Dave Mount @ UMD-CP

Bresenham's Algorithm

Given:

implicit line equation: $f(x, y) = ax + by + c = 0$

Let: $d_x = r_x - q_x$, $d_y = r_y - q_y$

where r and q are points on the line and d_x, d_y are positive

$$a = d_y, b = -d_x, c = -(q_x r_y - r_x q_y)$$

Then:

Observe that all of these are integers

and: $f(x, y) < 0$ for points above the line

$f(x, y) > 0$ for points below the line

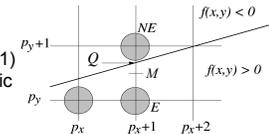
Now.....

21

PicaMath courtesy of Dave Mount @ UMD-CP

Bresenham's Algorithm

- Suppose we just finished (p_x, p_y)
 - (assume $0 \leq \text{slope} \leq 1$) other cases symmetric
- Which pixel next?
 - E or NE



East ($E = (p_x + 1, p_y)$)

NorthEast ($NE = (p_x + 1, p_y + 1)$)

22

PicaMath courtesy of Dave Mount @ UMD-CP

Bresenham's Algorithm

Assume:

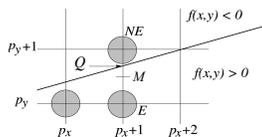
- $Q = \text{exact } y \text{ value at } x = p_x + 1$
- $y \text{ midway between } E \text{ and } NE: M = p_y + 1/2$

Observe:

If $Q < M$, then pick E

Else pick NE

If $Q = M$, it doesn't matter



23

PicaMath courtesy of Dave Mount @ UMD-CP

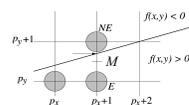
Bresenham's Algorithm

- Create "modified" implicit function ($2x$)
 $f(x, y) = 2ax + 2by + 2c = 0$
- Create a *decision variable* D to select, where D is the value of f at the midpoint:

$$D = f(p_x + 1, p_y + (1/2))$$

$$= 2a(p_x + 1) + 2b\left(p_y + \frac{1}{2}\right) + 2c$$

$$= 2ap_x + 2bp_y + (2a + b + 2c)$$

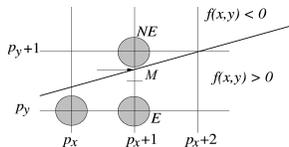


24

PicaMath courtesy of Dave Mount @ UMD-CP

Bresenham's Algorithm

- If $D > 0$ then M is below the line $f(x,y)$
 - NE is the closest pixel
- If $D \leq 0$ then M is above the line $f(x,y)$
 - E is the closest pixel



25

Bresenham's Algorithm

- If $D > 0$ then M is below the line $f(x,y)$
 - NE is the closest pixel
 - If $D \leq 0$ then M is above the line $f(x,y)$
 - E is the closest pixel
- Note: because we multiplied by $2x$, D is now an integer---which is very good news
- How do we make this incremental???

26

Case I: When E is next

- What increment for computing a new D ?
- Next midpoint is: $(p_x + 2, p_y + (1/2))$

$$\begin{aligned}
 D_{new} &= f(p_x + 2, p_y + (1/2)) \\
 &= 2a(p_x + 2) + 2b\left(p_y + \frac{1}{2}\right) + 2c \\
 &= 2ap_x + 2bp_y + (4a + b + 2c) \\
 &= 2ap_x + 2bp_y + (2a + b + 2c) + 2a \\
 &= D + 2a = D + 2d_y
 \end{aligned}$$

- Hence, increment by: $2d_y$

27

PicaMath courtesy of Dave Mount @ UMD-CP

Case II: When NE is next

- What increment for computing a new D ?
- Next midpoint is: $(p_x + 2, p_y + 1 + (1/2))$

$$\begin{aligned}
 D_{new} &= f(p_x + 2, p_y + 1 + (1/2)) \\
 &= 2a(p_x + 2) + 2b\left(p_y + \frac{3}{2}\right) + 2c \\
 &= 2ap_x + 2bp_y + (4a + 3b + 2c) \\
 &= 2ap_x + 2bp_y + (2a + b + 2c) + (2a + 2b) \\
 &= D + 2(a + b) = D + 2(d_y - d_x)
 \end{aligned}$$

- Hence, increment by: $2(d_y - d_x)$

28

PicaMath courtesy of Dave Mount @ UMD-CP

How to get an initial value for D ?

- Suppose we start at: (q_x, q_y)
- Initial midpoint is: $(q_x + 1, q_y + 1/2)$

Then:

$$\begin{aligned}
 D_{init} &= f(q_x + 1, q_y + 1/2) \\
 &= 2a(q_x + 1) + 2b\left(q_y + \frac{1}{2}\right) + 2c \\
 &= (2aq_x + 2bq_y + 2c) + (2a + b) \\
 &= 0 + 2a + b \\
 &= 2d_y - d_x
 \end{aligned}$$

29

PicaMath courtesy of Dave Mount @ UMD-CP

The Algorithm

```

void bresenham(IntPoint q, IntPoint r) {
    int dx, dy, D, x, y;
    dx = r.x - q.x; // line width and height
    dy = r.y - q.y;
    D = 2*d_y - dx; // initial decision value
    y = q.y; // start at (q.x, q.y)
    for (x = q.x; x <= r.x; x++) {
        writePixel(x, y);
        if (D <= 0) D += 2*d_y; // below midpoint - go to E
        else {
            D += 2*(d_y - dx); // above midpoint - go to NE
            y++;
        }
    }
}
    
```

Assumptions: $q_x < r_x$
 $0 \leq \text{slope} \leq 1$

Pre-computed: $2d_y$ $2(d_y - d_x)$

30

PicaMath courtesy of Dave Mount @ UMD-CP

Generalize Algorithm

- If $q_x > r_x$, swap points
- If slope > 1 , always increment y , conditionally increment x
- If $-1 \leq \text{slope} < 0$, always increment x , conditionally decrement y
- If slope < -1 , always decrement y , conditionally increment x
- Rework D increments

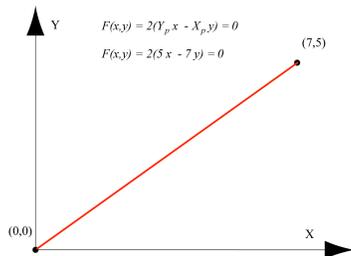
31

Generalize Algorithm

- Reflect line into first case
- Calculate pixels
- Reflect pixels back into original orientation

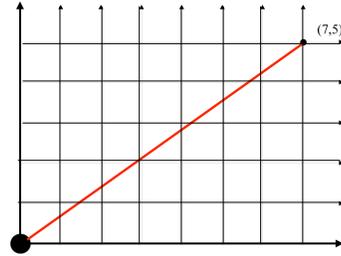
32

Bresenham's Algorithm: Example



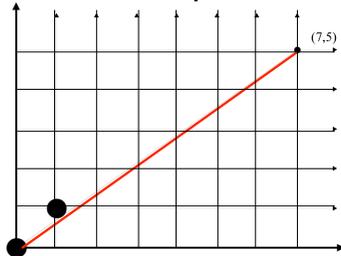
33

Bresenham's Algorithm: Example



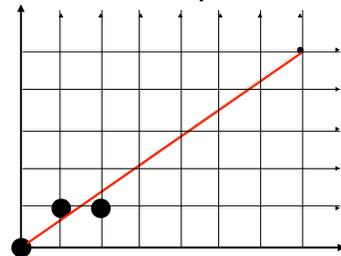
34

Bresenham's Algorithm: Example

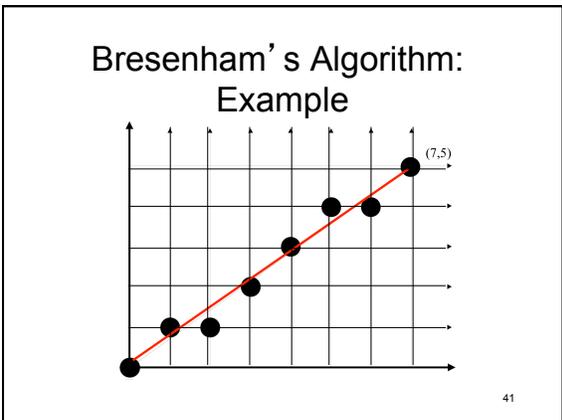
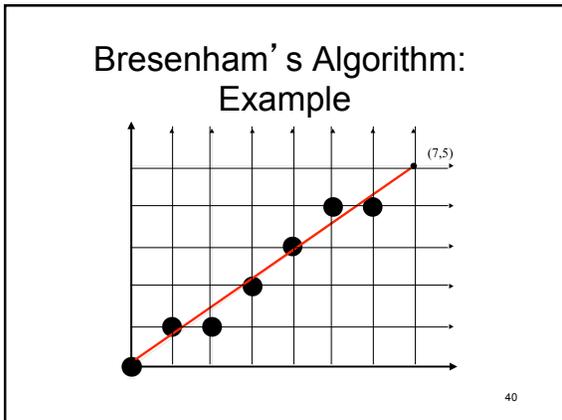
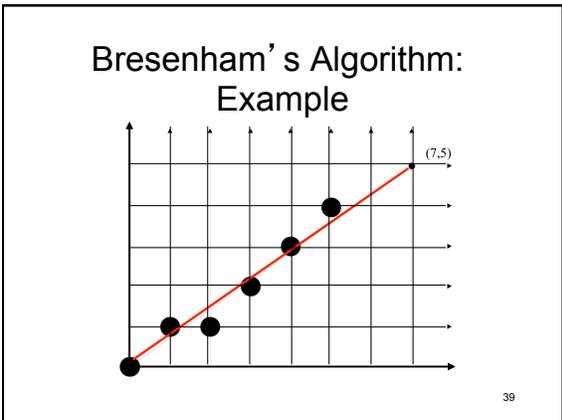
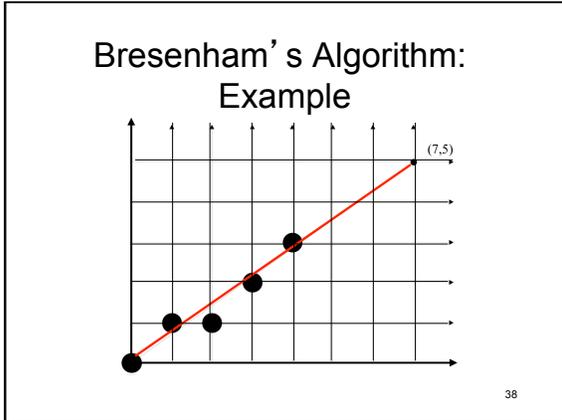
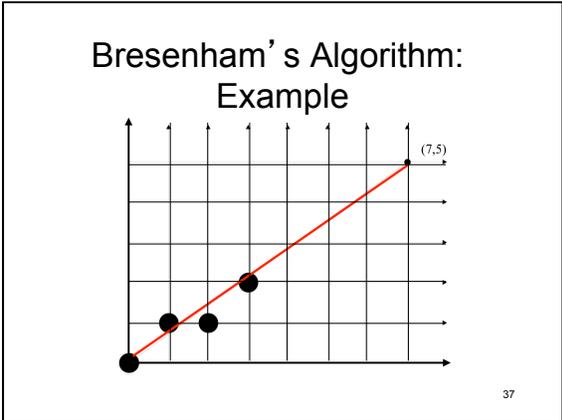


35

Bresenham's Algorithm: Example



36



Some issues with Bresenham's Algorithms

- Pixel 'density' varies based on slope
 - straight lines look darker, more pixels per unit length
 - Endpoint order
 - Line from P1 to P2 should match P2 to P1
 - Always choose *E* when hitting *M*, regardless of direction

42
1994 Foley/VanDam/Frame/Hughes/Phlips ICG

Programming assignment 1

- Input PostScript-like file
- Output B/W XPM
- Primary I/O formats for the course
- Create data structure to hold points and lines in memory (*the world model*)
- Implement 2D translation, rotation and scaling of the world model
- Implement line drawing and clipping
- January 20th
- Get started now!

51

Questions?

Go to Assignment 1

52